

# *diversity-radar introduction*

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<http://projects.openmoko.org/projects/diversity/>

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# *Agenda*

- Setup & Install python-efl and python-etk
  - How to use python setup tools to create a new project
  - How to interact with diversity-daemon
  - A scanning line animator
  - Set a timer to display flashing effects
  - Demo
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# *Setup & Install python-efl & python-etk*

- use 'get\_e.sh' shell script to install EFL  
[http://www.rasterman.com/files/get\\_e.sh](http://www.rasterman.com/files/get_e.sh)
  - use 'build\_all.sh' to install python-efl
  - `git://staff.get-e.org/users/cmarcelo/python-etk.git`
  - If e object is out of date, use 'cvs update -Pd', then make e objects again
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# *Distributing Python Modules I*

- \* tutorial: <http://docs.python.org/dist/dist.html>
- \* use Distutils to make python modules
- \* a 'setup.py' example

```
from setuptools import setup, find_packages, Extension
dist = setup(name='diversity-radar',
             version='0.04',
             author='Erin Yueh',
             package_dir={'': 'src'},
             packages=['radar'],
             scripts=['src/radar_ui.py'],
             data_files=[
                 ('diversity-radar/image',
                  ['data/image/gtk-add.png',
                  'data/image/gtk-
preferences.png', 'data/image/cc_blue.png']),
                 ('diversity-radar', ['data/theme/swallow.edj']),
                 ('applications', ['data/diversity-radar.desktop'])]
             )
```

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# *Distributing Python Modules*

## *II*

```
# python setup.py --help
Common commands: (see '--help-commands' for more)
  setup.py build      will build the package underneath
  'build/'
  setup.py install   will install the package

# python setup.py build
# python setup.py install --prefix=/usr
# python setup.py install_data --install-dir=/usr/share
```

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# *Between Diversity-daemon and Diversity-radar*

- \* use dbus to get the interactions with diversity-daemon
- \* python-dbus vs. python-edbus
- \* tutorial:

<http://dbus.freedesktop.org/doc/dbus-python/doc/tutorial.html>

```
import dbus
dbus.mainloop.glib.DBusGMainLoop(set_as_default=True)
bus = dbus.SessionBus()
```

```
world = dbus.Interface(
bus.get_object('org.openmoko.Diversity',
'/org/openmoko/Diversity/world'),
'org.openmoko.Diversity.World')
```

```
bard_path = world.GetSelf()
```

```
# register a callback for signal GeometryChanged
object_bard.connect_to_signal("GeometryChanged",
GeometryChanged_cb,
dbus_interface="org.openmoko.Diversity.Object")
```

# *Build the radar game*

World:

- \* `GetSelf()`: get NEOME self object and then can get its geometry location
- \* `ViewportAdd(x1,y1,x2,y2)` eg. `(-90.0,-90.0,180.0,180.0)`
- \* `TagAdd(x,y,description)` eg. `TagAdd(-40.1, -30.0, "Jeremy")`

Viewport:

- \* `ObjectAdded` signal: set a callback to create a target object
- \* `ObjectRemoved` signal: set a callback to remove a target object
- \* `Start()`: start viewport service and then can listen signals

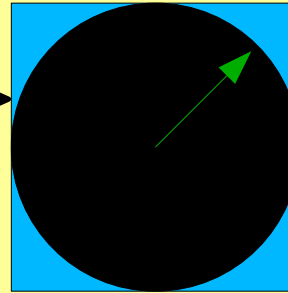
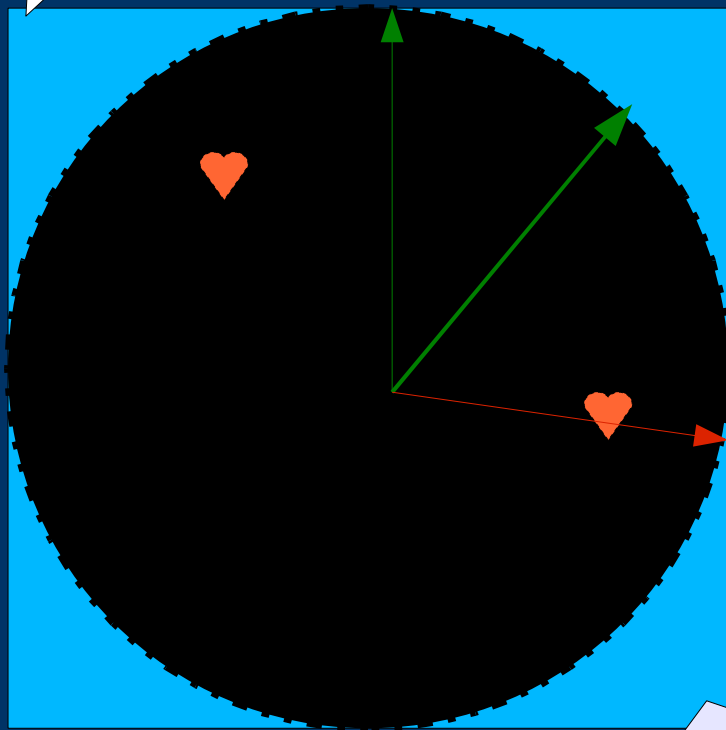
Object:

- \* `GetType()`: get the object type
  - \* `GeometrySet(lon,lat,w,h)`: set target real location in map
  - \* `GeometryGet()`
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# Build the radar map

$(x,y) = (0,0)$  UI coordinates

$(lon,lat) = (180,90)$



World map

$(lon,lat) = (-180,-90)$

$(x,y) = (480,480)$





# A Scanning Line Animator I

- UI coordinates vs. real world map (radius)  
`calObjectGeometryToCoord(self,lon,lat,bg,neome_lon,neome_lat,r)`
- $(lon - neome\_lon) / 2r = (x - center\_x) / w$
- $x = center\_x + (((lon - neome\_lon) / (2 * r)) * w)$
- $y = center\_y - (((lat - neome\_lat) / (2 * r)) * h)$
- Create a Line object in canvas
- `line_degree = line.data["degree"] +`  
`(ee.data["speed"] * (ecore.time_get() -`  
`line.data["last_time"]))`
- $x = center\_x + w * 0.5 * \text{math.cos}(line\_degree - (\text{math.pi} * 0.5))$
- $y = center\_y + h * 0.5 * \text{math.sin}(line\_degree - (\text{math.pi} * 0.5))$
- `line.xy_set(center_x, center_y, int(x), int(y))`

# A Scanning Line Animator II

- calculate the degree between center and object
  - `getObjectDegree(self, x0, y0, x, y):`
  - `degree = - (math.atan((x - x0) / (y - y0)))`
  - `obj_degree = target.get_degree(name)`
  - `if (math.fabs(obj_degree - line_degree) < 0.06):`
  - - `obj.geometry_set(int(x2), int(y2), int(w1), int(h1))`
  - `# change tag description position`
  - `text = obj.data["text"]`
  - `text.pos_set(x2+5, y2+5)`
  - `my_flash(obj)`
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# *A timer to display flashing image I*

```
def my_flash(obj):
    if(obj.data["flash_timer"]):
        obj.color_set(255,255,255,255)
        return
    obj.color_set(255,255,255,255) // set it bright
    obj.show()
    text = obj.data["text"]
    text.color_set(200,180,180,255)
    text.show()
    # run flash every 0.05 sec
    flash_timer = ecore.timer_add(0.05, flash,obj)
    obj.data["flash_timer"] = flash_timer
    obj.data["flag"] = 0 // set it to decrease alpha
    return True
```

# *A timer to display flashing image II*

```
def flash(obj):
    (r,g,b,alpha) = obj.color_get()
    text = obj.data["text"]
    if(obj.data["flag"] ==1): # fade in
        alpha+= 10
    elif(obj.data["flag"] ==0): # fade out
        alpha-= 10
    if(alpha>=255):
        obj.data["flag"] = 0
    elif(alpha<=0):
        obj.hide()
        text.color_set(180,20,100,255)
        obj.data["flash_timer"] = None
        return False
    obj.color_set(alpha,alpha,alpha,alpha)
    return True
```

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